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**ADVANCED PROCESS CONTROL****Course Code: 13CH2112**

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**PREREQUISITES:** The student should have knowledge of basics of control system and Laplace transforms.

**Course Educational Objectives:** This course enables the student

1. To design a controller to a single input single output and multi input and multi output plant.
2. Be able to understand the limitations of a controller design.

**Course Outcomes:** After completion of the course the student would be able to

1. Design a controller using advanced controller methods.
2. Understand the effect of model uncertainty in controller design.

**UNIT-I**

Review of single input single output (SISO) systems, Routh stability criteria. Frequency Response Analysis: Bode and Nyquist plots, effect of process parameters on Bode and Nyquist plots, closed loop stability concepts, Bode and Nyquist Stability.

**UNIT-II**

Internal Model control: Introduction to model based control, practical openloop controller design, generalization of the open-loop control design procedure, model uncertainty and disturbances. The IMC structure, IMC design procedure, effect of model uncertainty and disturbances. IMC in context of PID controller.

**UNIT-III**

Control-loop Interaction: Introduction, Motivation, the general pairing problem, the relative gain array, properties and application of the RGA. Multivariable Right Half Plane (RHP) Zeros and their performance limitations, Design of ideal Decouplers.

**UNIT-IV**

Model Predictive Control: Models forms of model predictive control, constrained and unconstrained approach, analysis of dynamic matrix control.

**UNIT-V**

State space and transfer function representation and their interrelationships. Sampling and Z-transforms, Open loop and closed loop response.

**TEXT BOOKS**

1. Wayne Bequette B., "*Process control: Modeling, Design and simulation*", PHI, 2003.
2. Stephanopoulos, "*Chemical Process Control: An Introduction to theory&Practices*", PHI, 2010

**REFERENCES:**

1. Ogunnaike, B., Ray W H, "*Process Dynamics, Modeling and Control*", Oxford University Press, 1994.
2. Seborg D.E. and Edgar T.F., Mellichamp D.A "*Process Dynamics and control*", Wiley, 2006.

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