SCHEME OF COURSE WORK

Course Details:

Course Title	:SOLID STATE CONTROL OF AC DRIVES						
Course Code	:13EE2215 L P C :4 03						
Program:	: Master of Technology.						
Specialization:	: Power Electronics & Drives						
Semester	: II						
Prerequisites	: Power Electronics and Power Electronics and Drives						
Courses to which it is a prerequisite : Research							

Course Outcomes (COs): After Completion of the course the student will be able to

1	Explain the Operation of induction motor and analyze speed control of AC Drives by VSI fed drives.
2	Analyze speed control of AC Drives by CSI fed drives and by slip power recovery drives
3	Analyze vector control of Induction motors
4	Analyze various control schemes to control speed of synchronous motor drives
5	Analyze various control schemes to control speed of PMSM drives and VRM Drives

Program Outcomes (POs):

The Graduates of will be able to:

1	Develop in depth knowledge in the areas of "Static Power Electronics Converters", "Power Electronic Converter fed Electrical Drives" and "Power Quality"
2	Apply soft computing techniques for Power Electronic Systems and Electric Drives
3	Understand large scale Power Electronic Converter Systems, Electric Drives and issues involved through Modeling, Analysis and Simulation
4	Apply present day techniques and tools to solve Power electronic and electric drives problems relevant to India and other countries
5	Use state-of-the-art simulation tools such as PLEXIM, SABER, OPAL-RT Lab, DSPACE, MULTISIM, LABVIEW and other Tools
6	Contribute positively to collaborative and multidisciplinary research to achieve common goals
7	Demonstrate knowledge and understanding of power engineering and management principles and apply the same for efficiently carrying out projects with due consideration to economical and financial factors
8	Communicate confidently, make effective presentations and write good reports to engineering community and society
9	Recognize the need for life-long learning and have the ability to do it independently
10	Acquire knowledge on social issues and shall contribute to the community for sustainable development
11	Predict and examine critically the outcomes of actions, apply corrective measures subsequently and move forward positively through a self corrective approach

Course Outcome Versus Program Outcomes:

Cos	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO-1	S	S	S	S	S	М	S	W	S		S
CO-2	S	S	S	S	S	S	S	W	S		S
CO-3	S	S	Μ	S	S	S	S	W	S		S
CO-4	S	S	Μ	S	S	S	S	W	S		S
CO-5	S	S	S	S	W	W	W	W	S		S

S - Strongly correlated, *M* - *Moderately* correlated, *Blank* - *No correlation*

Teaching-Learning and Evaluation

Week	TOPIC / CONTENTS	Course	Sample questions	TEACHING-	Assessment		
		Outcomes	T T T T T T T	LEARNING STRATEGY	Method & Schedule		
1	Review of steady-state operation of		Explain the equivalent Circuit of an	- Lootuno thuough	Cominau/Mid		
	torque-speed characteristics.	CO-1	Explain the speed torque	Black Board & LCD	Test		
			Characteristics of Induction	Discussion	(Week 9-10)		
	Coolar control Voltago fod Inverter control		Motor.	- Locture through	Cominar/Mid		
Z	Open loop volts/Hz control-Speed control with	CO-1	speed Control	Black Board & LCD	Test		
	slip regulation			Discussion	(Week 9-10)		
3	Speed control with torque and Flux control- Current controlled voltage fed Inverter Drive.		Explain the Speed control with torque and Flux control-Current	Lecture through	Seminar/Mid		
		CO-1	controlled voltage fed Inverter	Black Board & LCD	Test		
1	Current End Invertor control Independent		Drive.		(Week 9 10)		
т	current and frequency control		control of Induction Motor.	Lecture through	Seminar/Mid		
		CO-2	Explain the Independent current	Black Board & LCD	Test		
			and frequency control of Induction Motor.	Discussion	(Week 9-10)		
5	flux control in Current-Fed Inverter drive-		Explain the flux control in Current-				
	Volts/Hz control of Current Fed Inverter drive-		Fed Inverter drive of Induction				
	Effective optimization control by hax program,		Explain the Volts/Hz control of	Lecture through	Seminar/Mid		
		CO-2	Current Fed Inverter drive	Black Board & LCD	Test		
			Explain the Efficiency optimization	Discussion	(week 9-10)		
			control by flux program of				
6	Slin Power Recovery Drives-Static Kramer		Induction Motor. What is Slip Power and how it is				
Ũ	Drive-Phasor Diagram-Torque Expression-Speed		recovered?	I ecture through	Seminar/Mid		
	Control of Kramer Drive	CO-2	Explain the Static Kramer Drive-	Black Board & LCD	Test		
			Expression-Speed Control of	 Discussion 	(Week 9-10)		
			Kramer Drive				
/	Static Scherbius Drive Modes of Operation	CO-2	Explain the Static Scherbius Drive Modes of Operation	Lecture through Black Board & I CD	Seminar/Mid Test		
				 Discussion 	(Week 9-10)		
8	Principles of vector control	CO-3	What is the Principle of vector	Lecture through Black Board & LCD	Seminar/Mid		
			control	Discussion	(Week 9-10)		
9		Seminar by	the Students		Seminar (Week 9)		
10		Mid-Test	1		Week -10		
11	Direct vector control, derivation of indirect vector control implementation block diagram of		Explain the Direct vector control of Induction Motor	Lecture through	Seminar/Mid		
	indirect vector control	CO-3	Explain and Derive indirect	Black Board & LCD	Test		
			vector control of Induction Motor	Discussion	(Week 17-10)		
12	estimation of flux, flux weakening operation	CO-3	How the estimation of flux, flux weakening operation is done in the	Lecture through Black Board & LCD	Seminar/Mid Test		
			Induction motor	 Discussion 	(Week 17-18)		
13	Synchronous motor and its characteristics-		Explain the operation of an Synchronous motor	Lecture through	Seminar/Mid		
	control- power factor control, constant flux	CO-4	Explain the Various control	Black Board & LCD	Test		
14	control, flux weakening operation		strategies of Synchronous motor	Discussion	(WEEK 17-10)		
14	motor drive, motoring and regeneration,	<u> </u>	inverter fed synchronous motor	Lecture through	Seminar/Mid		
	phasor diagrams.	CO-4	drive , motoring and regeneration,	Black Board & LCD Discussion	lest (Week 17-18)		
15	Characteristics of permanent magnet		phasor diagrams	Biocassion	(1100)		
15	synchronous machines with permanent		permanent magnets	I ecture through	Sominar/Mid		
	magnet, vector control of PMSM- Motor model	CO-5	Explain the operation and control	Black Board & LCD	Test		
	anu controi scherne.			Discussion	(Week 17-18)		
			Explain the vector control of PMSM				
16	Variable Reluctance motor drives- Torque		Explain the operation of VRM				
	Drive characteristics and control principles		and control principles of VRM	 Lecture through Black Board & LCD 	Seminar/Mid		
	Current control variable reluctance motor servo	0-5	Explain the control principles of	Discussion	(Week 17-18)		
	urive		current control variable reluctance motor servo drive in detail				
17	STUDENTS SEMINAR						
18	Mid-Test 2						
19/20	END EXAM						