

SCHEME OF COURSE WORK

COURSE DETAILS:

Course Title	Introduction to Digital Signal Processing
Course Code	13EE1116
Program	B.Tech
Branch	Electrical & Electronics Engineering
Semester	VI
Prerequisites	Introduction to Signals & Systems
Course to which it is prerequisite	All Advanced Courses In Electrical Engineering

COURSE OUTCOMES:

CO1	Classify various types of discrete time signals and systems
CO2	Compute Discrete Fourier Series (DFS), Discrete time Fourier Transform (DTFT), Discrete Fourier Transform (DFT) and Fast Fourier Transform (FFT).
CO3	Design Infinite Impulse Response Filters
CO4	Design Finite Impulse Response Filters.
CO5	Describe the basics of DSP Processors.

The student of Electrical and Electronics Engineering at the end of the program will be able to:

1	Apply the knowledge of basic sciences and electrical and electronics engineering fundamentals to solve the problems of power systems and drives.
2	Analyze power systems that efficiently generate, transmit and distribute electrical power in the context of present Information and Communications Technology
3	Design and develop electrical machines and associated controls with due considerations to societal and environmental issues
4	Design and conduct experiments, analyze and interpret experimental data for performance analysis
5	Apply appropriate simulation tools for modeling and evaluation of electrical systems
6	Apply the electrical engineering knowledge to assess the health and safety issues and their consequences
7	Demonstrate electrical engineering principles for creating solutions for sustainable development
8	Develop a techno ethical personality that help to serve the people in general and Electrical and Electronics Engineering in particular
9	Develop leadership skills and work effectively in a team to achieve project objectives
10	Communicate effectively in both verbal and written form
11	Understand the principles of management and finance to manage project in multi disciplinary environments
12	Pursue life-long learning as a means of enhancing the knowledge and skills

COURSE OUTCOME/PROGRAM OUTCOMES:

CO'S	PO-1	PO-2	PO-3	PO-4	PO-5	PO-6	PO-7	PO-8	PO-9	PO-10	PO-11	PO-12
CO-1	M	M	M	M	M	M						M
CO-2	M	M	M	M	M	M						M
CO-3	M	M	M	M	M	M						M
CO-4	M	M	M	M	M	M						M
CO-5	M	M	M	M	M	M						M

Assessment Methods: Assignments/Quiz/Mid Exam/Seminar/Viva-Voce/End Exam

TEACHING LEARNING AND EVALUATION

We eks	Topic/content	CO	Sample questions	Teaching-learning strategy	Assessment method & schedule
1	<p style="text-align: center;">Unit-I</p> <p>INTRODUCTION:: Discrete – time signals and Systems, Representations, Elementary Signals, Basic Operations on signals, Classification of Signals, Classification of Discrete time systems.</p>	CO-1	<p>1). Test whether the following systems are linear or nonlinear, causal or non-Causal, and time variant or time-invariant and specify the reason.</p> <p>a). $y(n) = x^2(n) + \frac{1}{x^2(n-1)}$</p> <p>b). $y(n) = \log_{10} x(n)$</p> <p>2). Determine whether the following signals are energy signals, power signals or neither i) $x(n) = 2e^{j3n}$, ii) $x(n) = (-0.5)^n u(n)$ (2 marks)</p> <p>b) Determine whether the signals are periodic or not. If periodic find the fundamental period. i) $x(n) = \sin(n/9)$ and ii) $x(n) = \cos(2n/7)$.</p>	Lecture/discussion/n/problem solving	Assignment-1 & quiz- 1
2	Impulse Response and Convolution Sum, Convolution of Infinite sequences, Circular shift and Circular Symmetry.	CO-1	<p>1). Compute the following a) Linear convolution between $x(n) = \{1, 2, -1\}$ and $h(n) = \{2, 1, -2, 1\}$ b.) Find the convolution of $x(n) = \cos(n)u(n)$, $h(n) = (1/2)^n u(n)$</p>	Lecture/discussion/problem solving	Assignment-1 & quiz- 1
3	<p>Periodic or Circular Convolution. Methods of obtaining Circular Convolution Examples.</p> <p style="text-align: center;">unit-II</p> <p>DISCRETE FOURIER</p>	CO-1 CO-2	<p>1). Circular convolution between $x(n) = \{1, 1, 1, 1, -1, -1, -1, -1\}$ and $h(n) = \{0, 1, 2, 3, 4, 3, 2, 1\}$</p> <p>2). State and prove any three properties of DFS</p>	Lecture/discussion/problem solving	Assignment-1 & quiz- 1

	SERIES, DISCRETE TIME FOURIER TRANSFORM, DISCRETE FOURIER TRANSFORM & FAST FOURIER TRANSFORM Introduction, Discrete Fourier series, Properties of DFS.				
4	Discrete time Fourier transform, Relation between Z- Transform and DTFT, Inverse DTFT, Properties of DTFT, Frequency Response of DT Systems, Transfer Functions..	CO-2	1). a). The impulse response of a LTI system is $h(n)=\{1,2,1,-2\}$. Find the response of the system for input $x(n) = \{1,3,2,1\}$ using DTFT b). Find the DTFT of $\sin(n/2)$ $u(n)$ 2. find the IDFT of $X(k) = \{4,2,0,4\}$	Lecture/discussion /problem solving	Assignment-1 & quiz- 1
5	Discrete Fourier Transform, IDFT, Properties of DFT, Relation between Z- Transform and DFT, Linear Convolution and Circular Convolution using DFT.	CO-2	1). State and prove the Time Reversal, circular frequency shift , circular time shift properties of DFT 2. Find the 8-point DFT of $x(n) =$ $\{1,1\}$. Use the property of conjugate symmetry 3. computation of linear and circular convolution using DFT	Lecture/discussion /problem solving	Assignment-1 & quiz- 1
6	Fast Fourier Transform, Decimation in time radix – 2 FFT, Decimation in frequency radix1 – FFT, Butterfly Diagram, 8 – Point	CO-2 CO-3	1). compute the 8-point DFT by using Radix-2 DIT-FFT algorithm $x(n) =$ $\{0.5,0.5,0.5,0.5,0,0,0,0\}$ (2). compute the 8-point DFT by using Radix-2 DIF-FFT algorithm $x(n) = \{1,1,1,1\}$ 3. Given an analog filter transfer function $H(s) = 1/(s+1)$, use	Lecture/discussion /problem solving	Assignment-1 & quiz- 1

	<p>DFT Calculation.</p> <p>UNIT-III</p> <p>INFINITE</p> <p>IMPULSE</p> <p>RESPONSE</p> <p>FILTERS:</p> <p>Introduction, Analog Filter Fundamentals, Transformation methods, Design of IIR Filters, Low Pass Filter specifications,</p>		<p>impulse invariant method and obtain the digital filter transfer function.</p> <p>4. Obtain the relation between analog frequency and digital frequency in bilinear transformation? what is wrapping effect</p>		
7	<p>Design by approximation of derivatives, Impulse invariant transformation, Bilinear transformation, LP Butterworth digital filter</p>	CO-3	<p>1. Obtain a Butterworth digital IIR low pass filter transfer function impulse invariance by taking $T=0.5s$, to satisfy the following specifications.</p> $0.707 \leq H(\tilde{S}) \leq 1; \quad 0 \leq \tilde{S} \leq 0.45f_1$ $ H(\tilde{S}) \leq 0.2; \quad 0.65f \leq \tilde{S} \leq f_1$	Lecture/discussion /problem solving	Assignment-1 & quiz- 1
8	<p>Bilinear transformation, LP Butterworth digital filter</p>	CO-3	<p>1. Obtain a Butterworth digital IIR low pass filter transfer function using bilinear transformation by taking $T=0.5s$, to satisfy the following specifications.</p> $0.707 \leq H(\tilde{S}) \leq 1; \quad 0 \leq \tilde{S} \leq 0.45f_1$ $ H(\tilde{S}) \leq 0.2; \quad 0.65f \leq \tilde{S} \leq f_1$	Lecture/discussion /problem solving	Assignment-1 & quiz- 1
9	MID TEST-1				
10	<p>Chebyshev filter, Inverse Chebyshev filter, Elliptic filters, Frequency transformation.</p>	Co-3	<p>1). Design a Chebyshev low pass filter to meet the following specifications</p> <p>i). 1 dB ripple in pass band</p> $0 \leq \tilde{S} \leq 0.2f$ <p>ii) 25dB</p>	Lecture/discussion n/problem solving	Assignment-2 & quiz- 2

			attenuation in stop band $0.3f \leq \check{S} \leq f$ using Impulse invariance method. 2. write a short note on Elliptic Filters and Inverse Chyebshv filter		
11	Unit-IV FINITE IMPULSE RESPONSE FILTERS: Introduction, Characteristics of FIR filters with linear phase	CO-4	1). briefly explain the characteristics of FIR filters with linear phase	Lecture/discussion/ problem solving	Assignment- 2 & quiz- 2
12	Frequency response of linear phase FIR filters,	CO-4	1). Design a high pass FIR filter using hamming window with cutoff frequency of 1.2 rad/sec and Number of samples of the window is 9	Lecture/discussion /problem solving	Assignment- 2 & quiz- 2
13	Design of FIR filters using windows (Rectangular, Triangular, Raised Cosine, Hanning, Hamming, Blackman and Kaiser).	CO-4	1). Design a filter with $H_d(e^{j\check{S}}) = e^{-j3\check{S}} \text{ for } -\frac{\Pi}{4} \leq \check{S} \leq \frac{\Pi}{4}$ $= 0 \text{ for } \frac{\Pi}{4} \leq \check{S} \leq \frac{3\Pi}{4}$ Using a Hamming window N = 7 2. Design a filter with $H_d(e^{j\check{S}}) = e^{-j3\check{S}} \text{ for } -\frac{\Pi}{4} \leq \check{S} \leq \frac{\Pi}{4}$ $= 0 \text{ for } \frac{\Pi}{4} \leq \check{S} \leq \frac{3\Pi}{4}$ Using a Rectangular window N = 7	Lecture/discussion /problem solving	Assignment- 2 & quiz- 2
14	Unit-V INTRODUCTION TO DSP PROCESSORS Introduction, MAC operation	CO-5	advantages and disadvantages of DSP processors and MAC operation	Lecture/discussion	Assignment-2 & quiz- 2

15	Multiple Access Memory, VLIW architecture Special addressing modes	CO-5	1), Briefly explain the special addressing modes in P-DSPs 2. Explain the VLIW architecture with its block diagram.	Lecture/discussion	Assignment-2 & quiz-2
16	Pipelining On-chip peripherals	CO-5	1). Explain Pipelining concept 2). Explain on-chip peripherals	Lecture/discussion	Assignment-2 & quiz-2
17	Architecture of TMS320C5x.	CO-5	1). Explain TMS320C5X architecture with its block diagram		
18	MID Exam-2				
19, 20	End Exam	All co's			External exam